

Agenda

Introduction to threads

- Parallel computing

- Multi-core

What is a thread

Programming with threads (pthreads)

Summary: Process

What is a process?

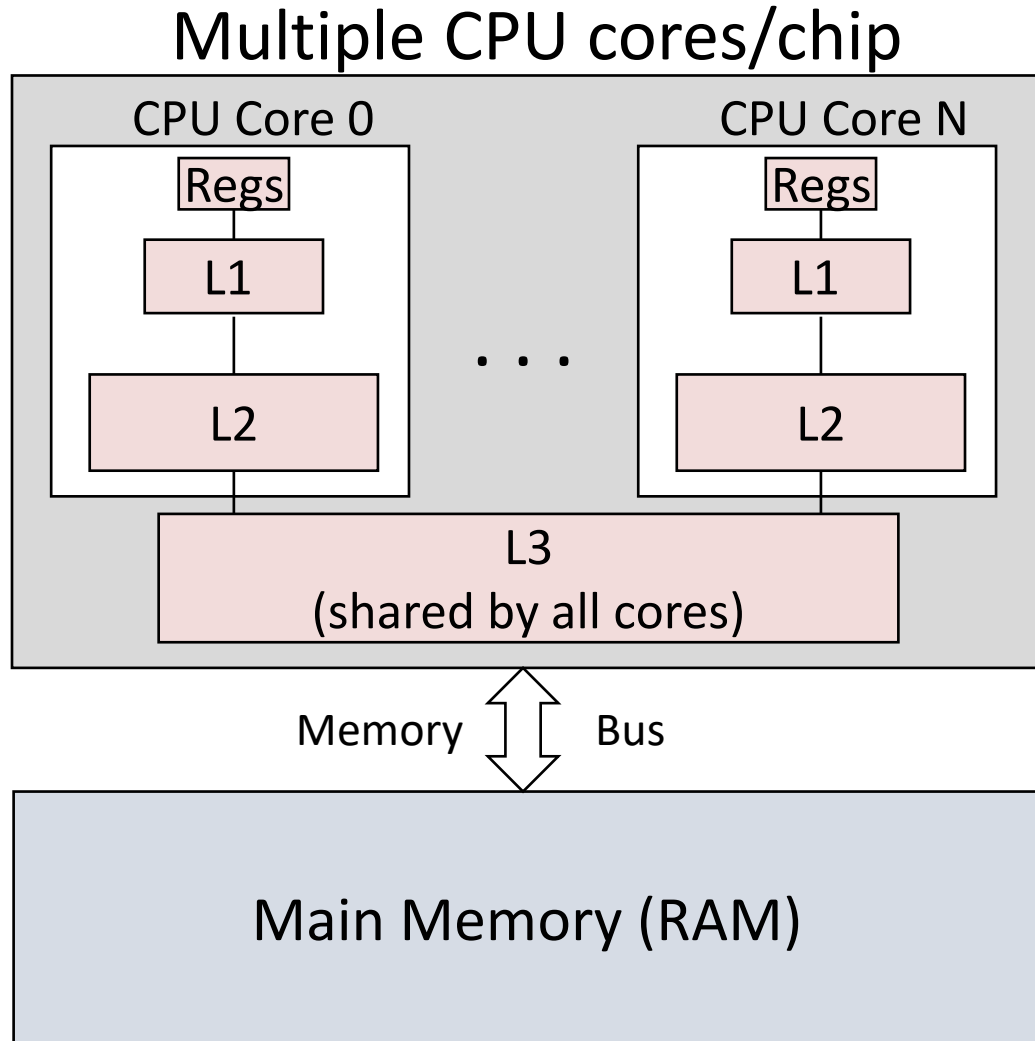
Advantages of processes:

- Abstraction: hardware easier to use for programmer/user
 - Maintains “lone view” of the system
 - Implements time sharing: each process gets small time slices of CPU
 - Implements virtual memory: simplifies programming model
- Efficiency:
 - Multiprogramming: 1+ running process at a time
 - Maximize use of hardware (disk/CPU)

Threads

- Multiple processes running on a single CPU give illusion of concurrency on a single machine
- Modern CPUs have multiple cores -> true concurrency!
- Threads allow a single process to execute segments of code concurrently across cores
 - Unlike processes, all threads share the same virtual memory space
 - Like processes, the OS handles scheduling of threads across multiple cores

Modern processors are Multi-core



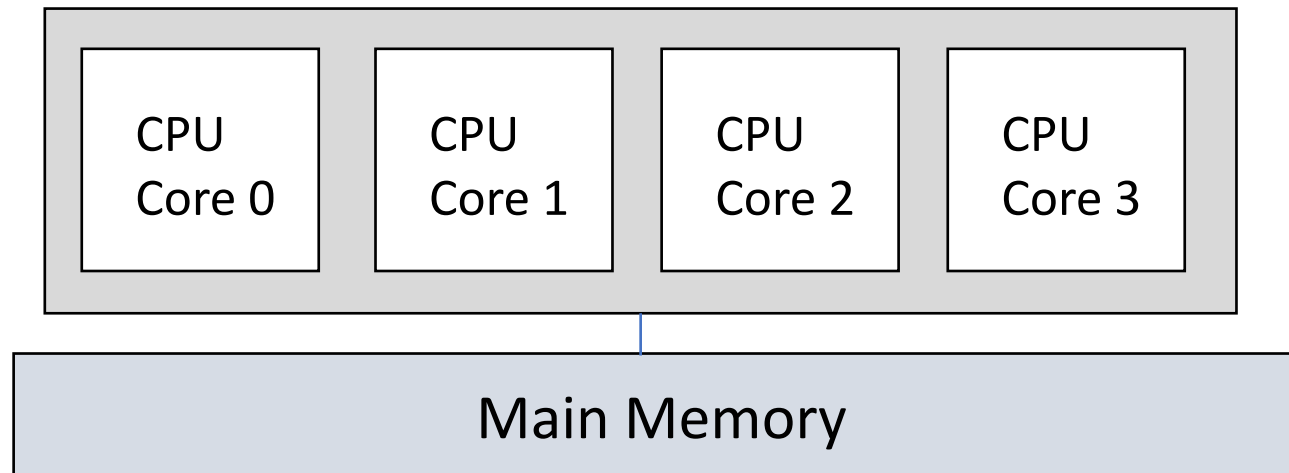
All CPU cores share
same Main
Memory

OS manages all
cores and
memory

RAM contains
process' VM
pages

Processes and Multicore

- OS schedules multiple processes to run simultaneously on separate CPU cores
 - On a 4-core processor, 4 concurrent processes can run at the same time, one per core
 - Get 4 times better throughput! (e.g. number of processes completed per hour)



Parallel Computing

- Splits problem processing into segments that can be run concurrently
- Part of Making Programs Run Faster
 - Been around for decades for scientific computing
 - 1960s and 1970s first parallel machines
 - Prior to ~2005 most chips single core (1 CPU)
 - Now all (almost all) are multi-core
 - Every computer today is a parallel computer (N CPUs)
- “Era of Big Data”
 - Many more large computational problems across more disciplines
 - Increasingly require large parallel and distributed solutions

Why Multi-core?

Because Moore's Law hit the Power/Heat Wall

Historically:

- Moore's Law: the number transistors/chip doubles about every 2 years

Transistor is building block on CPU (logic gates implemented with a few transistors)

Twice transistors means ~twice improvement

- Dennard Scaling: power use of these smaller transistors scales to area

Increase CPU clock speed every 2 years without increasing power!

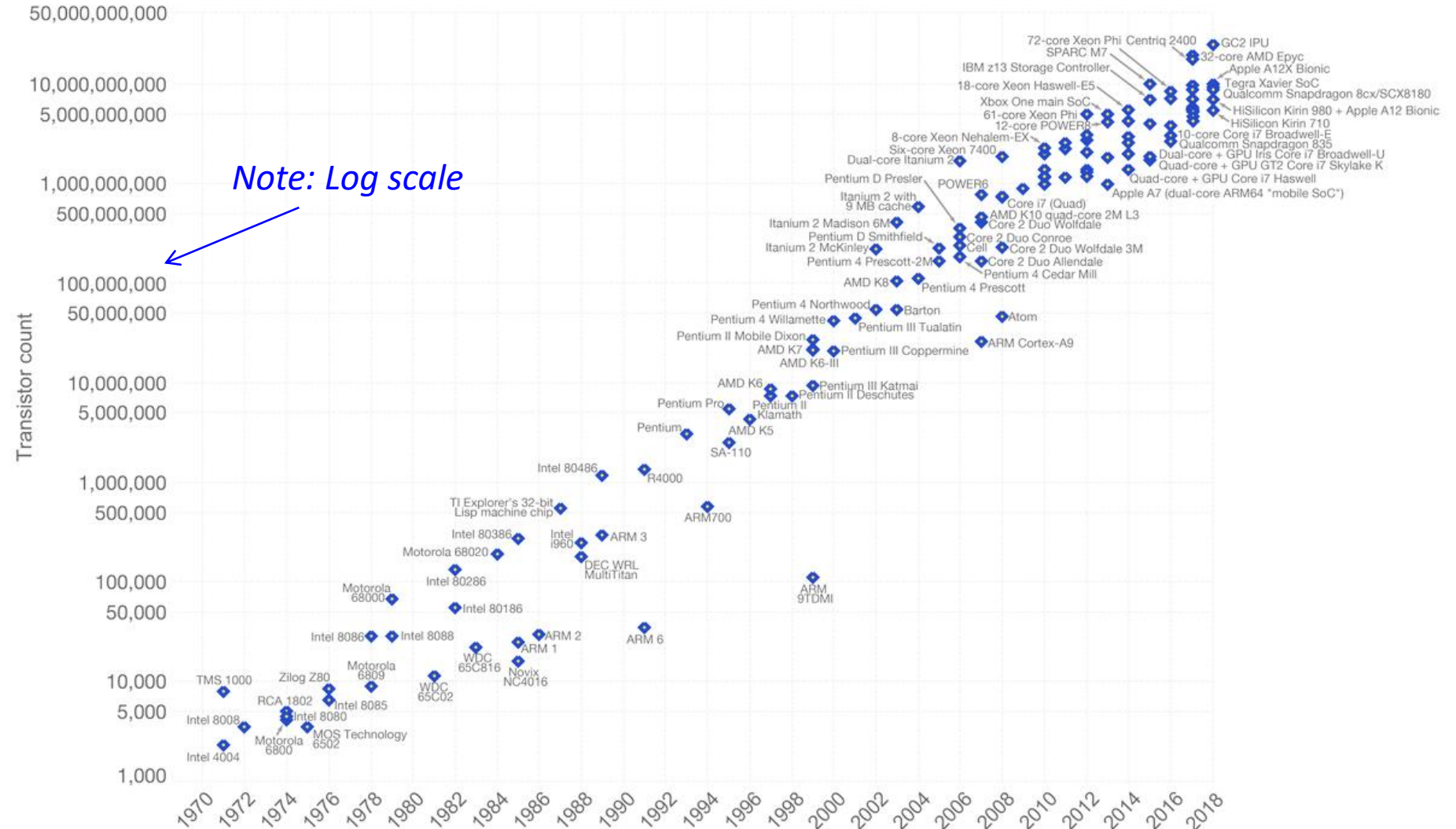
Why Multicore?

Moore's Law: still going strong!

The number of transistors/chip doubles about every 2 years!

Moore's Law – The number of transistors on integrated circuit chips (1971-2018)

Moore's law describes the empirical regularity that the number of transistors on integrated circuits doubles approximately every two years. This advancement is important as other aspects of technological progress – such as processing speed or the price of electronic products – are linked to Moore's law.



Data source: Wikipedia (https://en.wikipedia.org/wiki/Transistor_count)
The data visualization is available at [OurWorldinData.org](https://ourworldindata.org). There you find more visualizations and research on this topic.

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How to Double CPU performance

How to get 2x faster the old way (before 2005): ILP

Instruction Level Parallelism in single CPU core

Implicit parallelism (+ hidden from programmer)

- need faster clock cycle to drive:

but end of Dennard Scaling around this time

too much heat: hit the heat/power wall

How the new way: Multi-core

Multiple, “simple” CPU cores on chip

Same clock speed each generation of chip

Explicit Parallelism to make single program run faster

- programmer and OS need to explicitly use them

Parallel Computing

Speed up a program by dividing it up into parts, each part runs in parallel on multiple CPUs

++ 10 hours on 1 CPU → 6 mins on 100 CPUs!!! (maybe)

- OS needs to implement abstractions to support (Threads)

- To schedule on multiple CPUs to get parallel execution
- To allow parallel components to share execution state

- Programmer must explicitly use

- Need a language/library for expressing parallelism
 - Need to come up with parallelization strategy
- Parallel algorithm & assess efficiency of parallelization

Not always easy or even possible

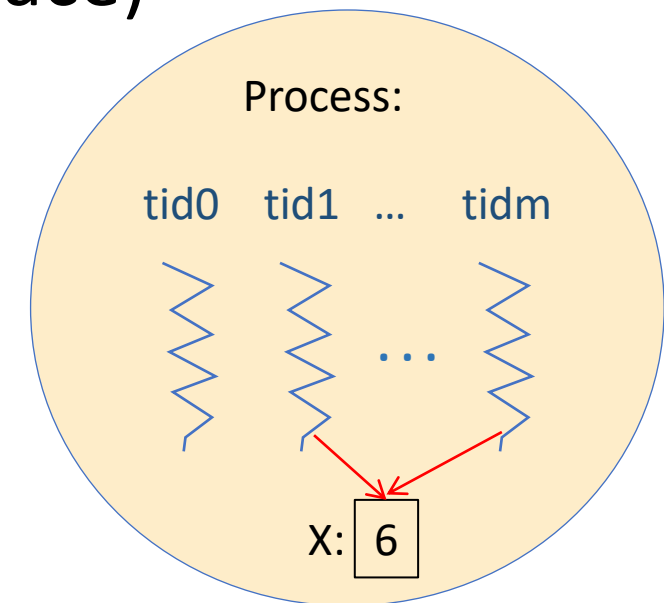
OS Abstraction: Thread

Thread: a stream of execution in a process

Multi-threaded process: multiple concurrent streams of execution in a single process

(all execute in a single shared virtual address space)

NOTE: writing a multi-threaded application is easier than a multi-process application because threads all have access to the same view of memory (processes need special mechanisms – pipes, shared memory, sockets – to coordinate)

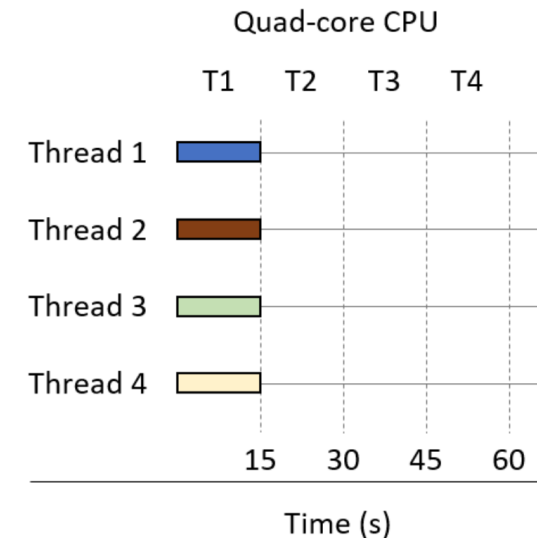
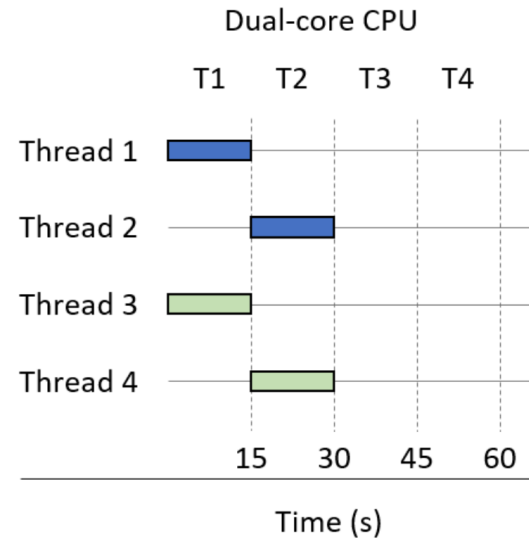
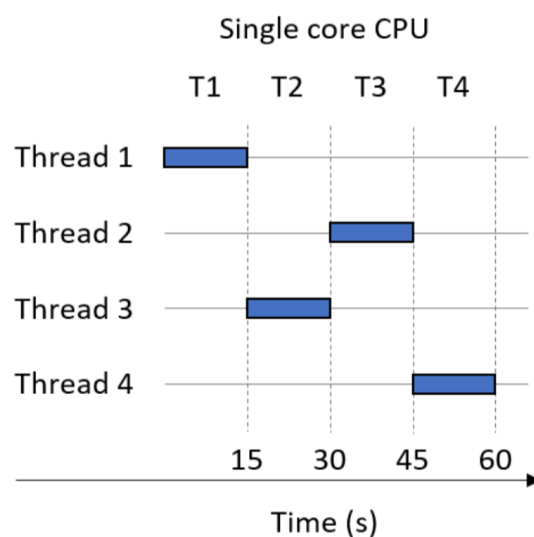


Threads Example

A **thread** is a stream of execution within a process

```
void scalar_multiply(int * array, long length, int s) {  
    for (int i = 0; i < length; i++) {  
        array[i] = array[i] * s;  
    }  
}
```

1. Create t threads.
2. Assign each thread a subset of the input array (i.e., N/t elements).
3. Instruct each thread to multiply the elements in its array subset by s



OS Abstraction: Thread

Threads are all part of a single Process:

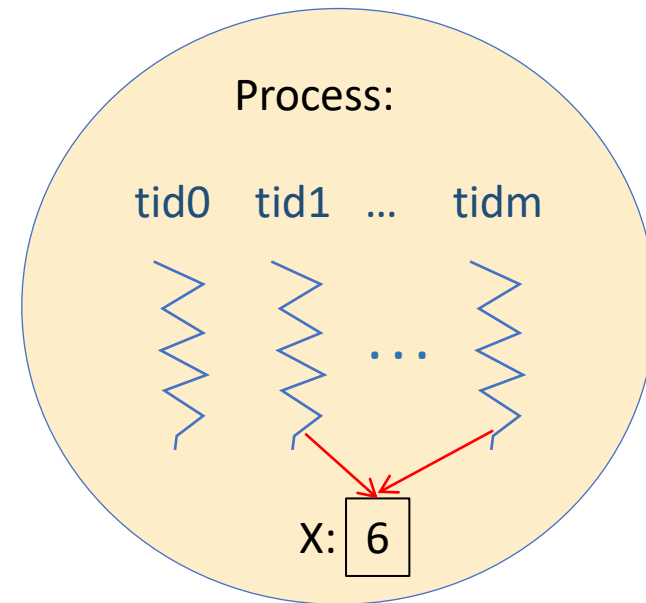
- Communicate using Shared Address Space

thread 1: set x to 6 (write x)

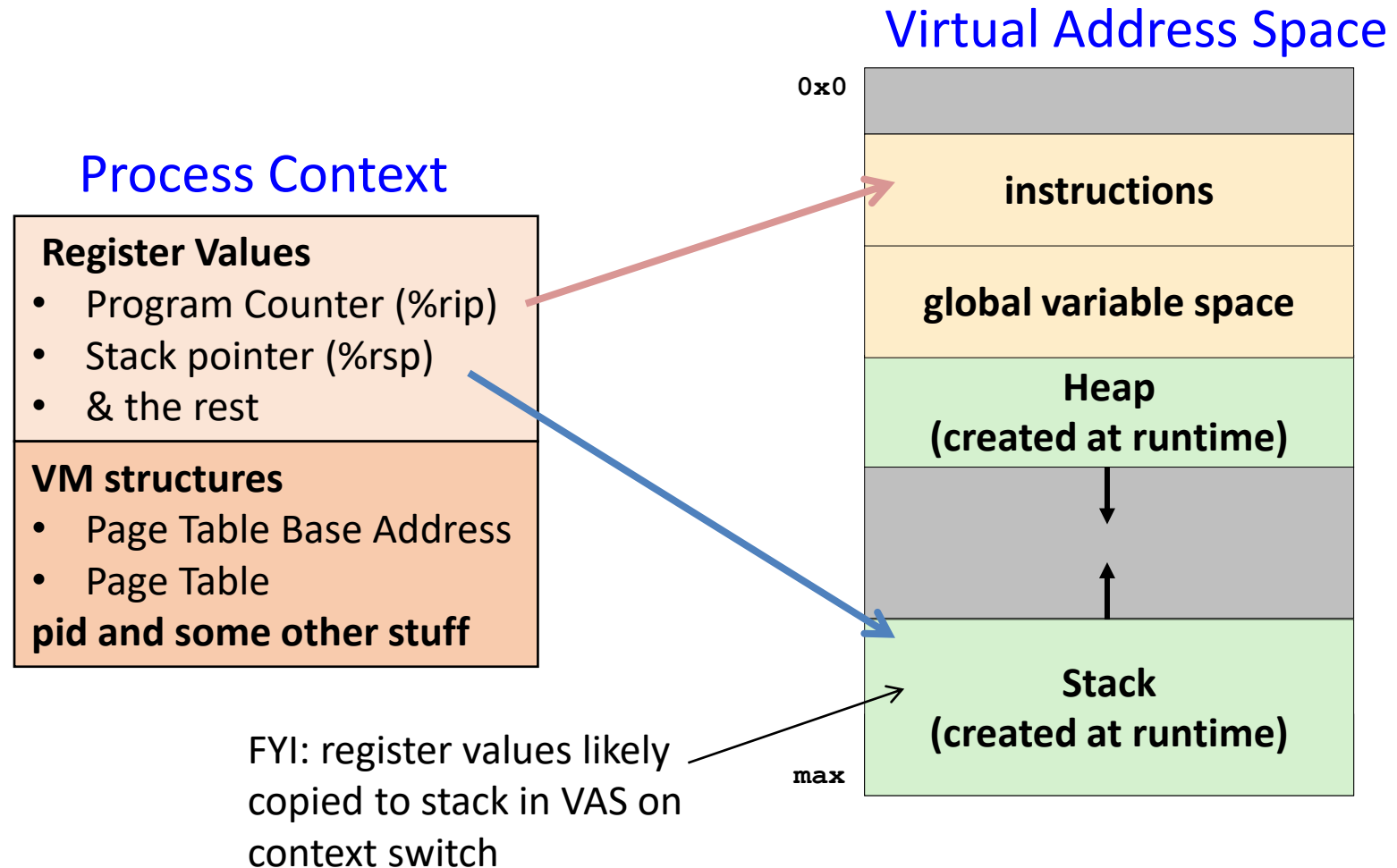
thread m: get value of x (read x)

- OS can schedule each thread to run on a different CPU on multi-core (can run simultaneously)

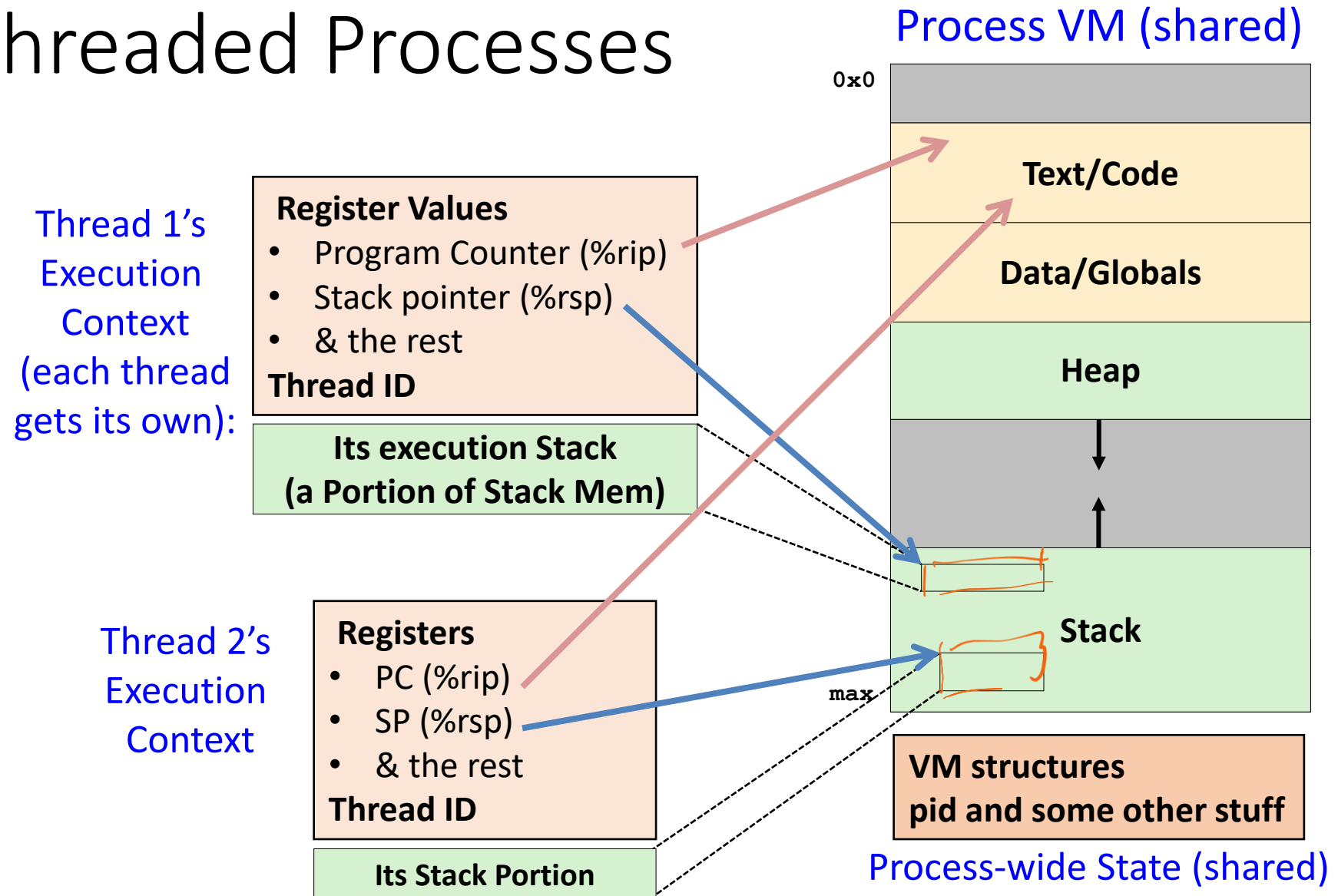
+ parallel execution of threads



Single Process Execution State

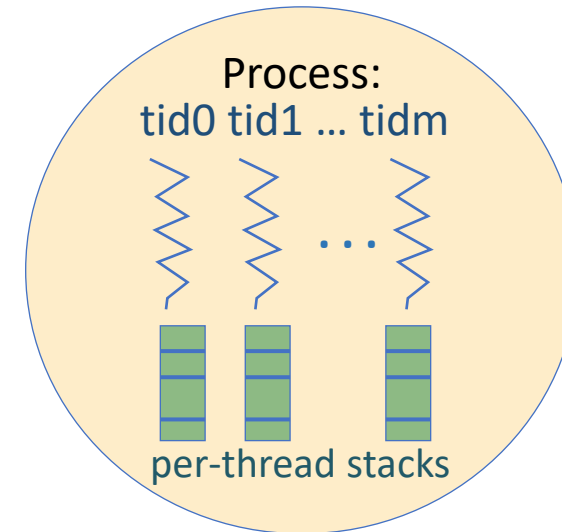


Multi-Threaded Processes



Threads

- Private: tid, copy of registers, execution stack
- Shared: everything else in the process
 - + Sharing is easy
 - + Sharing is cheap
 - no data copy from one P_i's virtual address space to another P_j's virtual address space
 - + Thread create & CXS faster than process
 - All share same virtual address space, page table
 - + OS can schedule on multiple CPUs of multicore
 - + **Parallelism**
 - Coordination/Synchronization
 - How to not muck-up each other's state
 - Can only use on systems with shared physical memory (can't if cooperating P_is are on different computers)



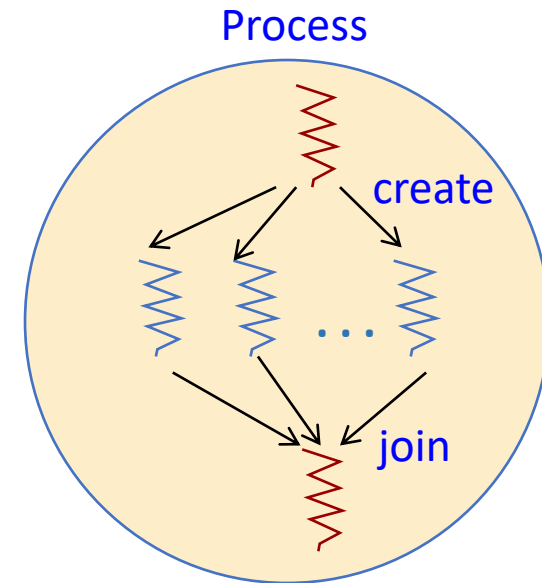
Programming Threads

Every Process has 1 thread of execution

- The single **main thread** executes from beginning

A common threaded execution model:

1. Main thread often initializes shared state first
2. Then **spawns/creates** multiple threads
3. Set of threads execute **concurrently** to perform some task
4. Main thread may do a **join**, to wait for other threads to exit (~wait to reap exited threads)
5. Main thread may do some final sequential processing (like write results to a file)



Demo: HelloThread

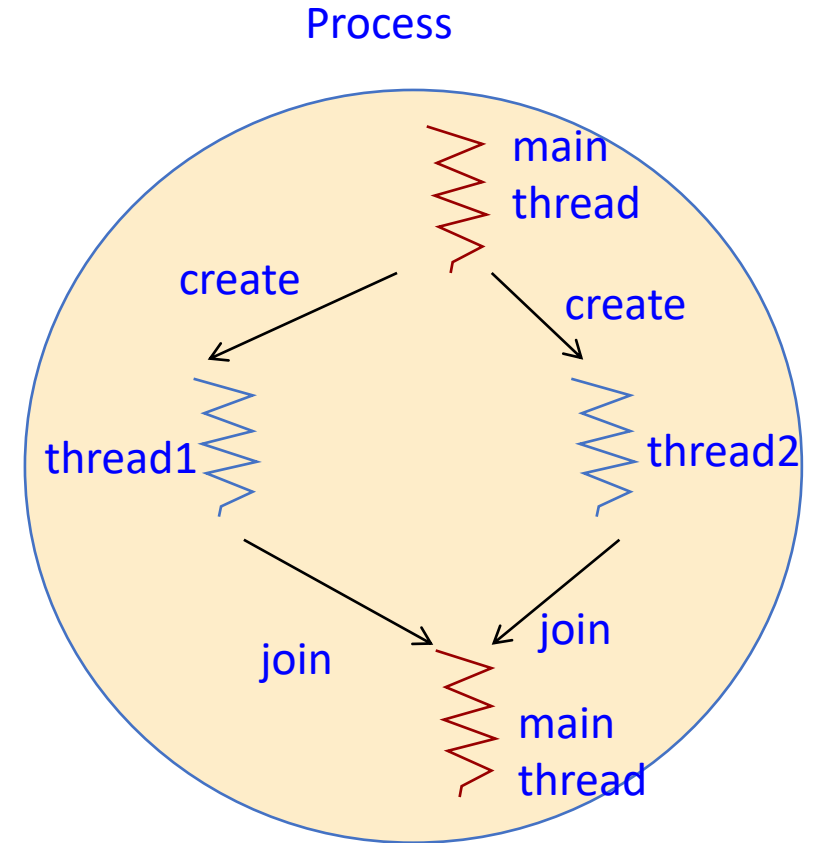
```
5 void *HelloWorld(void *id) {
6     long *myid = (long *) id;
7     printf("Hello world! I am thread %ld\n", *myid);
8     return NULL;
9 }
10
11 int main(int argc, char **argv) {
12     long id1 = 1, id2 = 2;
13     long* retval1 = NULL, *retval2 = NULL;
14     pthread_t thread1, thread2;
15     pthread_create(&thread1, NULL, HelloWorld, &id1);
16     pthread_create(&thread2, NULL, HelloWorld, &id2);
17     pthread_join(thread1, NULL);
18     pthread_join(thread2, NULL);
19     return 0;
20 }
```

gcc thread-hello.c -lpthread

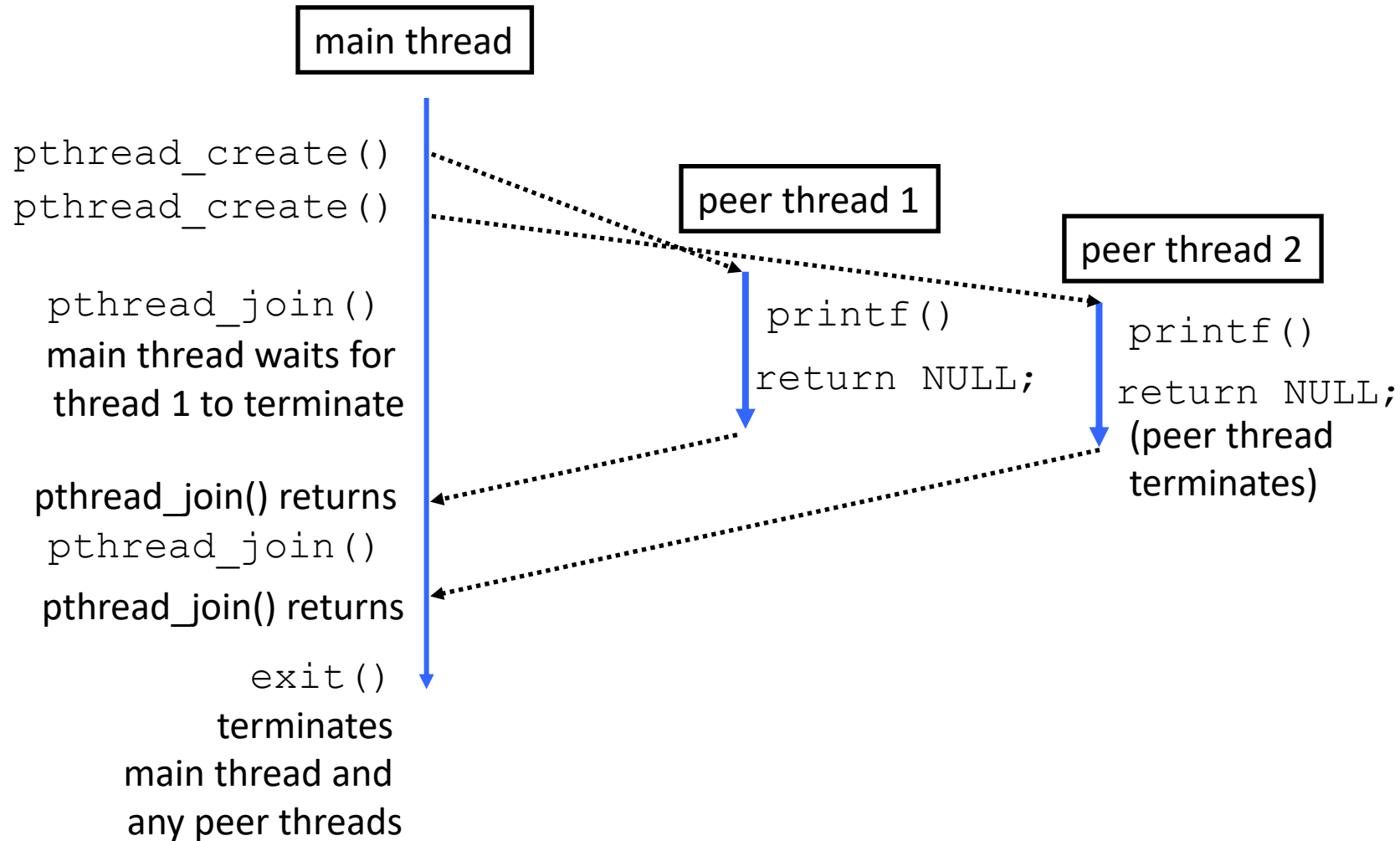
Visualizing HelloThread

Which lines of code are executed by which thread?

- main thread executes lines 12-16
- each thread executes lines 6-8
- main thread waits for thread 1 (line 17)
- main thread waits for thread 2 (line 18)
- main thread returns and exits (line 19)



Visualizing HelloThread: concurrent execution



Common pthread functions

Creating a thread (starts running start func w/passed args):

```
int pthread_create(pthread_t *thread,  
                  pthread_attr_t *attr,  
                  void *(*start_func)(void *),  
                  void *args);
```

Joining (reaping) a thread (caller waits for thread to exit):

```
int pthread_join(pthread_t thrd, void **retval);
```

Terminating a thread:

```
void pthread_exit(void *retval)
```

(or just return from thread's main function)

Pthreads

PThreads: The **POSIX** threading interface

- The **P**ortable **O**perating **S**ystem **I**nterface for **UNIX**
- A standard Interface to OS utilities
 - system calls have same prototype & semantics on all Oses
 - (ex) POSIX compliant code on Solaris will compile on Linux

Pthreads library contains functions for:

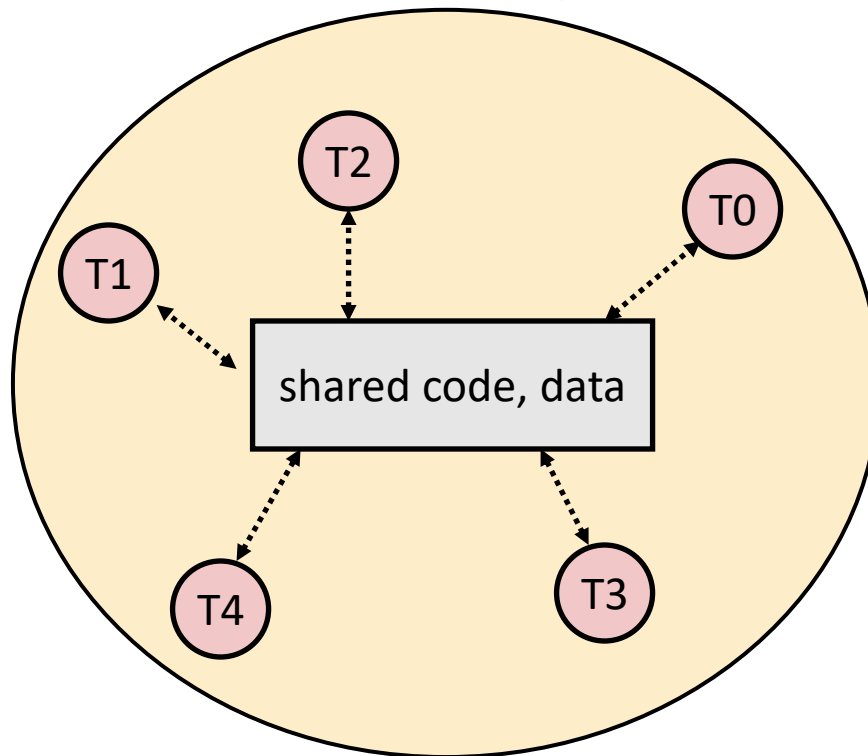
- Creating threads (and thread exit)
- Synchronizing threads
 - Coordinating their access to shared state

To compile: `gcc myprog.c -lpthread`

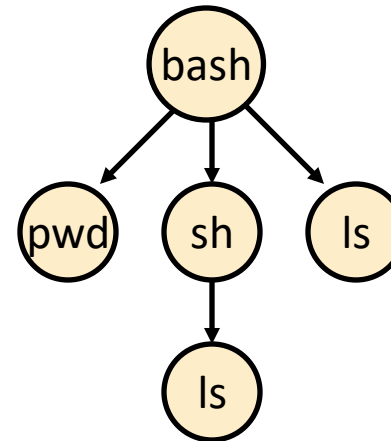
Logical View of Threads

- Threads form a pool of peers w/in a process
(Unlike processes which form a tree hierarchy)

Threads within one process



Process hierarchy



Draw a stack diagram: HelloWorld

```
5 void *HelloWorld(void *id) {  
6     long *myid = (long *) id;  
7     printf("Hello world! I am thread %ld\n", *myid);  
8     return NULL;  
9 }  
10  
11 int main(int argc, char **argv) {  
12     long id1 = 1, id2 = 2;  
13     long* retval1 = NULL, retval2 = NULL;  
14     pthread_t thread1, thread2;  
15     pthread_create(&thread1, NULL, HelloWorld, &id1);  
16     pthread_create(&thread2, NULL, HelloWorld, &id2);  
17     pthread_join(thread1, NULL);  
18     pthread_join(thread2, NULL);  
19     return 0;  
20 }
```


Visualizing Thread execution: HelloThread

```
5 void *HelloWorld(void *id) {
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17     pthread_join(thread1, NULL);
18     pthread_join(thread2, NULL);
19     return 0;
20 }
```

Summary: Comparing fork() vs threads

Fork()

- Each process has its own memory
- Programmer must decide how to split work and coordinate processes
 - External mechanisms: shmem, pipes, sockets, wait, signals
- Concurrent code has no guarantees on the order it runs

Threads

- Each thread shares memory in same process
- Programmer must decide how to split work and coordinate threads
 - Built-in mechanisms: mutex, barrier, wait
- Concurrent code has no guarantees on the order it runs

Exercise: Design a multi-threaded program

Parallel Compute Min

- Large array of size N of int values
- M threads (assume $N \gg M$), and $N \% M$ is 0

Some Questions to Consider:

1. What part of total operation does each thread do?
2. How does a thread know which work it will do?
3. Do threads need to coordinate their actions in any way?
4. What global/shared state do you need? What local state?

Design

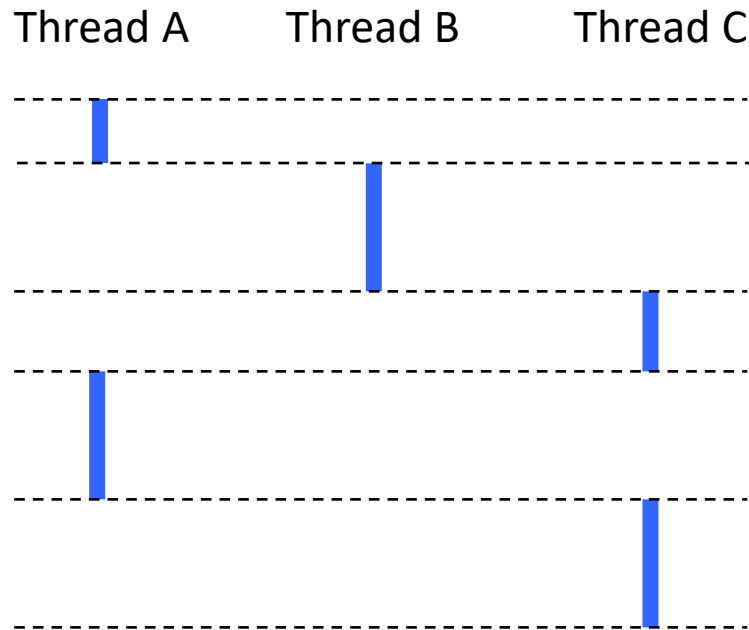
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Thread Concurrency

Threads' Execution Control Flows Overlap

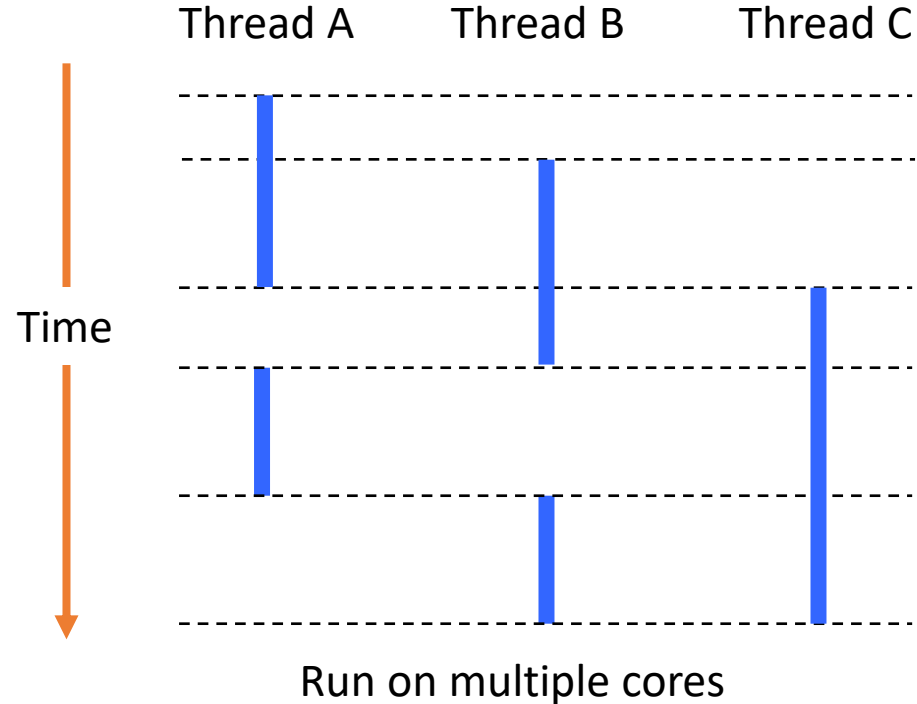
Single Core Processor

Concurrent w/time slicing



Multi-Core Processor

True parallel execution



Exercise

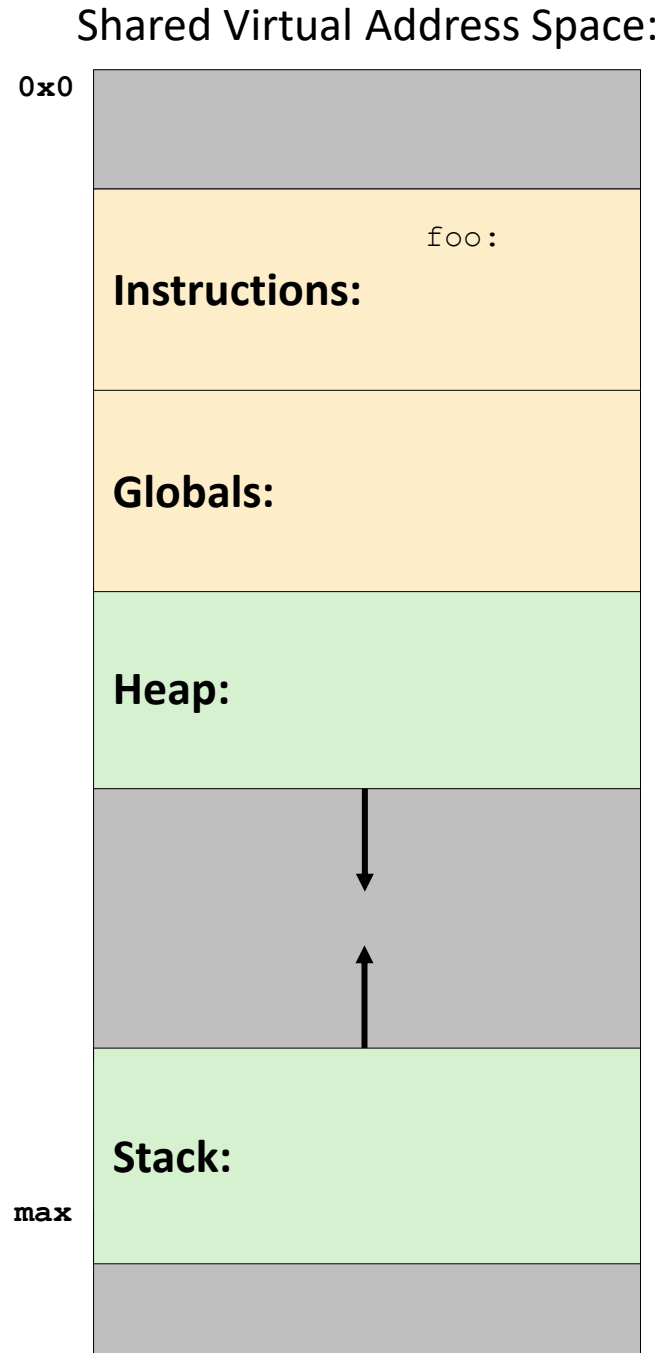
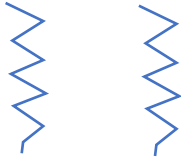
```
static int x;  
  
int foo(int *p) {  
    int y;  
  
    y = 3;  
    y = *p;  
    *p = 7;  
    x += y;  
}
```

If threads i and j both execute function foo code:

Q1: which variables do they each get own copy of? which do they share?

Q2: which stmts can affect values seen by the other thread?

Tid i Tid j



Exercise: Draw a stack diagram

```
static int x;

int foo(int *p) {
    int y;

    y = 3;
    y = *p;
    *p = 7;
    x += y;
}

int main() {
    int pvalue = 35;
    pthread_t thread1, thread2;
    pthread_create(&thread1, NULL, foo, &pvalue);
    pthread_create(&thread2, NULL, foo, &pvalue);
    pthread_join(thread1, NULL);
    pthread_join(thread2, NULL);
    return 0;
}
```

Stack Diagram: Possibility 1

```
static int x = 0;

int foo(int *p) {
    int y;

    y = 3;
    y = *p;
    *p = 7;
    x += y;
}

int main() {
    int pvalue = 35;
    pthread_t thread1, thread2;
    pthread_create(&thread1, NULL, foo, &pvalue);
    pthread_create(&thread2, NULL, foo, &pvalue);
    pthread_join(thread1, NULL);
    pthread_join(thread2, NULL);
    return 0;
}
```


Stack Diagram: Possibility 2

```
static int x = 0;

int foo(int *p) {
    int y;

    y = 3;
    y = *p;
    *p = 7;
    x += y;
}

int main() {
    int pvalue = 35;
    pthread_t thread1, thread2;
    pthread_create(&thread1, NULL, foo, &pvalue);
    pthread_create(&thread2, NULL, foo, &pvalue);
    pthread_join(thread1, NULL);
    pthread_join(thread2, NULL);
    return 0;
}
```